

Stern- und  
Planetенentstehung  
Sommersemester 2020  
Markus Röllig

Lecture 4: Gravitational Instability and Collapse



[http://exp-astro.physik.uni-frankfurt.de/star\\_formation/index.php](http://exp-astro.physik.uni-frankfurt.de/star_formation/index.php)

## VORLESUNG/LECTURE

Raum: Physik - 02.201a

dienstags, 12:00 - 14:00 Uhr

## SPRECHSTUNDE:

Raum: GSC, 1/34, Tel.: 47433, (roellig@ph1.uni-koeln.de)

dienstags: 14:00-16:00 Uhr

Nr.	Thema	Termin
1	Observing the cold ISM	21.04.2020
2	Observing Young Stars	28.04.2020
3	Gas Flows and Turbulence Magnetic Fields and Magnetized Turbulence	05.05.2020
4	Gravitational Instability and Collapse	12.05.2020
5	Stellar Feedback	19.05.2020
6	Giant Molecular Clouds	26.05.2020
7	Star Formation Rate at Galactic Scales	02.06.2020
8	Stellar Clustering	09.06.2020
9	Initial Mass Function – Observations and Theory	16.06.2020
10	Massive Star Formation	23.06.2020
11	Protostellar disks and outflows – observations and theory	30.06.2020
12	Protostar Formation and Evolution	07.07.2020
13	Late Stage stars and disks – planet formation	14.07.2020

## 4 GRAVITATIONAL INSTABILITY AND COLLAPSE

So far we ignored gravity!

### 4.1 THE VIRIAL THEOREM

Assume the MHD equations with no viscosity and no resistivity (both unimportant on large scales)

$$\frac{\partial}{\partial t} \rho = -\nabla \cdot (\rho \vec{v})$$
$$\frac{\partial}{\partial t} (\rho \vec{v}) = -\nabla \cdot (\rho \vec{v} \vec{v}) - \nabla P + \frac{1}{4\pi} (\nabla \times \vec{B}) \times \vec{B} - \underline{\rho \nabla \phi}$$

here,  $\phi$  is the gravitational potential, so  $-\rho \nabla \phi$  is the grav. force per unit volume. These are the Eulerian equations (in conservative form).

To simplify them we rewrite them in tensorial form. We define two tensors:

the fluid pressure tensor

$$\boldsymbol{\Pi} \equiv \rho \vec{v} \vec{v} + P \underline{\boldsymbol{I}}$$

the Maxwell stress tensor (2<sup>nd</sup> rank)

$$\boldsymbol{T}_M \equiv \frac{1}{4\pi} \left( \vec{B} \vec{B} - \frac{B^2}{2} \boldsymbol{I} \right)$$

( $\boldsymbol{I}$  is the identity tensor). In tensor notation the two are:

$$(\boldsymbol{\Pi})_{ij} \equiv \rho v_i v_j + P \delta_{ij}$$
$$(\boldsymbol{T}_M)_{ij} \equiv \frac{1}{4\pi} \left( B_i B_j - \frac{1}{2} B_k B_k \delta_{ij} \right)$$

Now the momentum equation is:

$$\frac{\partial}{\partial t} (\rho \vec{v}) = -\nabla \cdot (\underline{\boldsymbol{\Pi}} - \boldsymbol{T}_M) - \rho \nabla \phi$$

because:

$$(\nabla \times \vec{B}) \times \vec{B} = \epsilon_{ijk} \epsilon_{jmn} \left( \frac{\partial}{\partial x_m} B_n \right) B_k$$
$$= -\epsilon_{jik} \epsilon_{jmn} \left( \frac{\partial}{\partial x_m} B_n \right) B_k$$

$$\begin{aligned}
&= (\delta_{in}\delta_{km} - \delta_{im}\delta_{kn}) \left( \frac{\partial}{\partial x_m} B_n \right) B_k \\
&= B_k \frac{\partial}{\partial x_k} B_i - B_k \frac{\partial}{\partial x_i} B_k \\
&= \left( B_k \frac{\partial}{\partial x_k} B_i + B_i \frac{\partial}{\partial x_k} B_k \right) - B_k \frac{\partial}{\partial x_i} B_k \\
&= \frac{\partial}{\partial x_k} (B_i B_k) - \frac{1}{2} \frac{\partial}{\partial x_i} (B_k^2) \\
&= \nabla \cdot \left( \vec{B} \vec{B} - \frac{B^2}{2} \right)
\end{aligned}$$

Tensor notation insert:

$$\begin{aligned}
(\vec{a} \times \vec{b}) \cdot \vec{c} &= \sum_{i=1}^3 (\vec{a} \times \vec{b})_i \cdot c_i = \sum_{i=1}^3 \sum_{j=1}^3 \sum_{k=1}^3 \epsilon_{ijk} a_j b_k c_i \\
(\vec{a} \times \vec{b})_i &= \sum_{j=1}^3 \sum_{k=1}^3 \epsilon_{ijk} a_j b_k c_i = \epsilon_{ijk} a_j b_k c_i \\
\Rightarrow \vec{a} \times \vec{b} &= \epsilon_{ijk} a_j b_k \vec{e}_j = \epsilon_{ijk} a_i b_j \vec{e}_k \\
(\vec{a} \times \vec{b}) \cdot \vec{c} &= \epsilon_{ijk} a_i b_j c_k
\end{aligned}$$

Example:

$$\epsilon_{123} = \vec{e}_1 \cdot (\vec{e}_2 \times \vec{e}_3) = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \cdot \left( \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right) = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = 1$$

|  $\epsilon_{ijk}$ : Levi-Cita symbol (permutation symbol)

$$\epsilon_{ijk} = \begin{cases} 1, & \text{even permutation} \\ -1, & \text{odd permutation} \\ 0, & \text{double indices} \end{cases} \quad \begin{aligned} \epsilon_{123} &= \epsilon_{312} = \epsilon_{231} = 1 \\ \epsilon_{321} &= \epsilon_{213} = \epsilon_{132} = -1 \end{aligned}$$

"Eselsbrücke":

123123 (reading from left +1, from right -1)

Kronecker-delta:

$$\delta_{ij} = \begin{cases} 1, & i = j \\ 0, & i \neq j \end{cases}$$

$$\begin{aligned}
\epsilon_{ijk}\epsilon_{lmn} &= \begin{vmatrix} \delta_{il} & \delta_{im} & \delta_{in} \\ \delta_{jl} & \delta_{jm} & \delta_{jn} \\ \delta_{kl} & \delta_{km} & \delta_{kn} \end{vmatrix} \\
&= \delta_{il}\delta_{jm}\delta_{kn} + \delta_{im}\delta_{jn}\delta_{kl} + \delta_{in}\delta_{jl}\delta_{km} - \delta_{im}\delta_{jl}\delta_{kn} \\
&\quad - \delta_{il}\delta_{jn}\delta_{km} - \delta_{in}\delta_{jm}\delta_{kl} \\
\epsilon_{ijk}\epsilon_{imn} &= \begin{vmatrix} \delta_{jm} & \delta_{jn} \\ \delta_{km} & \delta_{kn} \end{vmatrix} = \delta_{jm}\delta_{kn} - \delta_{jn}\delta_{km} \\
\epsilon_{ijk}\epsilon_{ijn} &= 2\delta_{kn} \\
\epsilon_{ijk}\epsilon_{ijk} &= 3! = 6
\end{aligned}$$

Imagine a gas cloud enclosed in some fixed volume  $V$ . The surface of the cloud is  $S$ . To specify how the overall distribution of mass inside  $V$  changes we write down the moment of inertia:

$$I = \int_V \rho r^2 dV$$

Its change over time is

$$\begin{aligned}
\frac{\partial}{\partial t} I &= \dot{I} = \int_V \frac{\partial \rho}{\partial t} r^2 dV \quad | \\
&= - \int_V \nabla \cdot (\rho \vec{v}) r^2 dV \\
&= - \int_V \nabla \cdot (\rho \vec{v} r^2) dV + 2 \int_V \rho \vec{v} \cdot \vec{r} dV \\
&= - \int_S (\rho \vec{v} r^2) \cdot dS + 2 \int_V \rho \vec{v} \cdot \vec{r} dV \quad |
\end{aligned}$$

(1<sup>st</sup> step:  $V$  is constant, derivative inside integral, 2<sup>nd</sup> step: equation of mass conservation, 3<sup>rd</sup> step:  $r^2$  inside divergence, 4<sup>th</sup> step: divergence theorem to replace volume with surface integral).

Second time derivative (times  $\frac{1}{2}$ ):       

$$\begin{aligned}
\ddot{I} &= - \frac{1}{2} \int_S r^2 \frac{\partial}{\partial t} (\rho \vec{v}) \cdot dS + \int_V \frac{\partial}{\partial t} (\rho \vec{v}) \cdot \vec{r} dV \\
&= - \frac{1}{2} \frac{d}{dt} \int_S r^2 (\rho \vec{v}) \cdot dS - \int_V \vec{r} \cdot [\nabla \cdot (\Pi - \mathbf{T}_M) + \rho \nabla \phi] dV \quad |
\end{aligned}$$

For any tensor  $\mathbf{T}$  the following holds:

$$\begin{aligned}
\int_V \vec{r} \cdot \nabla \cdot \mathbf{T} dV &= \int_V x_i \frac{\partial}{\partial x_j} T_{ij} dV \\
&= \int_V \frac{\partial}{\partial x_j} (x_i T_{ij}) dV - \int_V T_{ij} \frac{\partial}{\partial x_j} x_i dV \\
&= \int_S x_i T_{ij} dS_j - \int_V \delta_{ij} T_{ij} dV \\
&= \int_S \vec{r} \cdot \mathbf{T} \cdot d\mathbf{S} - \int_V \text{Tr } \mathbf{T} dV
\end{aligned}$$

where  $\text{Tr } \mathbf{T} = T_{ii}$  is the trace of the Tensor  $\mathbf{T}$ .

We note that

$$\begin{aligned}
\text{Tr } \mathbf{\Pi} &= 3P + \rho v^2 \\
\text{Tr } \mathbf{T}_M &= -\frac{B^2}{8\pi}
\end{aligned}$$

Inserting this give the virial theorem. Introducing some new terms it reads:

$$\boxed{\frac{1}{2} \ddot{I}} = 2(\mathcal{T} - \mathcal{T}_S) + \mathcal{B} + \mathcal{W} - \frac{1}{2} \frac{d}{dt} \int_S (\rho \vec{v} r^2) \cdot d\mathbf{S}$$

where:

$$\begin{aligned}
\mathcal{T} &= \int_V \left( \frac{1}{2} \rho v^2 + \frac{3}{2} P \right) dV \\
\mathcal{T}_S &= \int_S \vec{r} \cdot \mathbf{\Pi} \cdot d\mathbf{S} \\
\mathcal{B} &= \frac{1}{8\pi} \int_V B^2 dV + \int_S \vec{r} \cdot \mathbf{T}_M \cdot d\mathbf{S} \\
\mathcal{W} &= - \int_V \rho \vec{r} \cdot \nabla \phi dV
\end{aligned}$$

$\mathcal{T}$ : total kinetic energy plus thermal energy of the cloud

$\mathcal{T}_S$ : confining pressure on the cloud surface (including thermal pressure and ram pressure of any gas flowing through the surface)

$\mathcal{B}$ : difference between the magn. pressure in the cloud interior

(stabilizing) and the magn. pressure plus magn. tension at the cloud surface (trying to collapse).

$\mathcal{W}$ : gravitational energy of the cloud (gravitational binding energy + possibly some external grav. field)

$\frac{1}{2} \frac{d}{dt} \int_S (\rho \vec{v} r^2) \cdot d\mathbf{S}$ : rate of change of momentum flux across the cloud surface.

$\ddot{\mathcal{I}}$  is the integrated form of the acceleration. For a cloud of fixed shape it tells us the rate of change of the cloud's expansion or contraction.

$\ddot{\mathcal{I}} < 0$ : the terms trying to collapse the cloud are larger  
cloud accelerates inward

$\ddot{\mathcal{I}} > 0$ : the terms that favor expansion are larger  
cloud accelerates outward

$\ddot{\mathcal{I}} = 0$ : cloud is stable

If no gas crosses the cloud surface ( $\vec{v} = 0$  at  $S$ ) and uniform magn. field  $B_0$  at the surface:

$$\frac{1}{2} \ddot{\mathcal{I}} = 2(\mathcal{T} - \mathcal{T}_S) + \mathcal{B} + \mathcal{W}$$

with

$$\begin{aligned}\mathcal{T}_S &= \int_S r P dS \\ \mathcal{B} &= \frac{1}{8\pi} \int_V (B^2 - B_0^2) dV\end{aligned}$$

now  $\mathcal{T}_S$  is just the mean radius times pressure at the virial surface and  $\mathcal{B}$  just represents the total magn. energy of the cloud minus the magnetic energy of the ambient magnetic background field over the same volume.

In equilibrium ( $\ddot{\mathcal{I}} = 0$ ) and if magnetic and surface forces are negligible we have

$$2\mathcal{T} = -\mathcal{W}$$

We define the virial ratio

$$\alpha_{vir} = \frac{2\mathcal{T}}{|\mathcal{W}|}$$

$\alpha_{vir} > 1$  implies  $\ddot{I} > 0$

$\alpha_{vir} < 1$  implies  $\ddot{I} < 0$

$\alpha_{vir} = 1$  separates clouds that have enough internal pressure or turbulence to avoid collapse from those that do not.

## 4.2 STABILITY CONDITIONS

The virial theorem will help us to understand qualitatively, under what conditions a cloud of gas will be stable against gravitational contraction, and under what conditions it will not be.

$$\frac{1}{2}\ddot{I} = 2(\mathcal{T} - \underline{\mathcal{T}_S}) + \underline{\mathcal{B}} + \underline{\mathcal{W}} - \frac{1}{2}\frac{d}{dt} \int_S (\rho \vec{v} r^2) \cdot dS$$

Opposing collapse:

- $\mathcal{T}$  (thermal pressure and turbulent motion)
- $\mathcal{B}$  (magnetic pressure and tension)

Favoring collapse:

- $\mathcal{W}$  (self-gravity)
- $\mathcal{T}_S$  (surface pressure)

The surface term (last term on right side) can be positive or negative depending on whether mass is flowing in or out.

### 4.2.1 Thermal Support and the Jeans Instability

Quick estimate:

Gas pressure always tries to smooth out the gas -> counter collapse

Self-gravity always promotes collapse

expected line between stability and instability:  $\alpha_{vir} \approx 1$

isolated, isothermal cloud of Mass  $M$  and radius  $R$ :

$$\mathcal{T} = \frac{3}{2} M c_s^2$$

$$\mathcal{W} = -a \frac{GM^2}{R}$$

$a$ : depends on internal density structure (of order unity)

$$\underline{\alpha_{vir} \gtrsim 1} \quad M c_s^2 \gtrsim \frac{GM^2}{R} \Rightarrow \boxed{R \gtrsim \frac{GM}{c_s^2}}$$

$$\text{or, using the mean density } \rho \sim M/R^3 \quad \underline{\underline{R \gtrsim \frac{c_s}{\sqrt{G\rho}}}}$$

Full formal analysis (Jeans (1902))

Consider a uniform, infinite, isothermal medium at rest:

(density:  $\rho_0$ , pressure:  $P_0 = \rho_0 c_s^2$ , velocity:  $\vec{v}_0 = 0$ )

Equations of HD and self-gravity:

$$\frac{\partial}{\partial t} \rho + \nabla \cdot (\rho \vec{v}) = 0$$

$$\frac{\partial}{\partial t} (\rho \vec{v}) + \nabla \cdot (\rho \vec{v} \vec{v}) = -\nabla P - \rho \nabla \phi$$

$$\underline{\nabla^2 \phi = 4\pi G \rho}$$

conservation of mass

conservation of momentum

Poisson eq. for grav. potential  $\phi$

$\phi_0, \rho_0, \vec{v}_0, P_0$ : exact solutions and  $\partial/\partial t \rightarrow 0$  if gas is not perturbed

(*Jeans swindle*: There is no function  $\phi_0$  such that  $\nabla^2 \phi_0$  is equal to a non-zero constant value on all space. Approximation to a finite uniform medium)

Perturbation:  $\epsilon \ll 1$

$$\rho = \rho_0 + \epsilon \rho_1, \quad \vec{v} = \epsilon \vec{v}_1, \text{ and} \quad \phi = \phi_0 + \epsilon \phi_1$$

We assume a simple, single Fourier mode as perturbation form (simplifies solutions of DEQs):

$$\underline{\rho_1} = \rho_a \exp[i(kx - \omega t)] \quad | \quad \text{use only } \operatorname{Re}(\rho_1)$$

coordinate system choice: wave vector  $\vec{k}$  is in the direction of the  $\vec{x}$  direction

density perturbation  $\rightarrow$  which potential perturbation?

$$\nabla^2(\phi_0 + \epsilon \phi_1) = 4\pi G(\rho_0 + \epsilon \rho_1) \quad |$$

since  $\boxed{\nabla^2 \phi_0 = 4\pi G \rho_0}$

$$\nabla^2 \epsilon \phi_1 = 4\pi G \epsilon \rho_1$$

$$\nabla^2 \phi_1 = 4\pi G \rho_a \exp[i(kx - \omega t)]$$

$$\Rightarrow \phi_1 = -\frac{4\pi G \rho_a}{k^2} \exp[i(kx - \omega t)]$$

$\phi_1 = \phi_a \exp[i(kx - \omega t)]$ , therefore:

$$\boxed{\phi_a = -\frac{4\pi G \rho_a}{k^2}}$$

What motion does this induce?  $\swarrow \searrow$

- Insert  $\rho = \rho_0 + \epsilon \rho_1$ ,  $\vec{v} = \epsilon \vec{v}_1$ ,  $P = P_0 + \epsilon P_1 = c_s^2(\rho_0 + \epsilon \rho_1)$  and  $\phi = \phi_0 + \epsilon \phi_1$  into conservation equations
- linearize them, i.e. expand in powers of  $\epsilon$  and drop all term of order  $\epsilon^2$  and higher, since they become very small

$$\frac{\partial}{\partial t}(\rho_0 + \epsilon \rho_1) + \nabla \cdot [(\rho_0 + \epsilon \rho_1)(\epsilon \vec{v}_1)] = 0$$

$$\cancel{\frac{\partial}{\partial t} \rho_0} + \epsilon \frac{\partial}{\partial t} \rho_1 + \epsilon \nabla \cdot (\rho_0 \vec{v}_1) = 0$$

$$\underline{\underline{\rho_0 = \text{const}}}$$

$$\frac{\partial}{\partial t} \rho_1 + \nabla \cdot (\rho_0 \vec{v}_1) = 0$$

and

$$\begin{aligned} \frac{\partial}{\partial t} [(\rho_0 + \epsilon \rho_1)(\epsilon \vec{v}_1)] + \nabla \cdot [(\rho_0 + \epsilon \rho_1)(\epsilon \vec{v}_1)(\epsilon \vec{v}_1)] \\ = -c_s^2 \nabla (\rho_0 + \epsilon \rho_1) - (\rho_0 + \epsilon \rho_1) \nabla (\phi_0 + \epsilon \phi_1) \\ \epsilon \frac{\partial}{\partial t} (\rho_0 \vec{v}_1) = -c_s^2 \nabla \rho_0 - \rho_0 \nabla \phi_0 - \epsilon (c_s^2 \nabla \rho_1 + \rho_1 \nabla \phi_0 + \rho_0 \nabla \phi_1) \\ \frac{\partial}{\partial t} (\rho_0 \vec{v}_1) = -c_s^2 \nabla \rho_1 - \rho_0 \nabla \phi_1 \end{aligned}$$

$$\boxed{\begin{array}{l} \rho_0 = \text{const} \\ \phi_0 = \text{const} \end{array}}$$

We assume again:  $\vec{v}_1 = \vec{v}_a \exp[i(kx - \omega t)]$

$$\frac{\partial}{\partial t} (\rho_a \exp[i(kx - \omega t)]) + \nabla \cdot (\rho_0 \vec{v}_a \exp[i(kx - \omega t)]) = 0$$

$$-i\omega \rho_a \exp[i(kx - \omega t)] + ik \rho_0 v_{a,x} \exp[i(kx - \omega t)] = 0$$

$$-\omega \rho_a + k \rho_0 v_{a,x} = 0$$

$v_{a,x}$ : x component of  $\vec{v}_a$

$$\boxed{v_{a,x} = \frac{\omega \rho_a}{k \rho_0}}$$

$$\frac{\partial}{\partial t} (\rho_0 \vec{v}_a \exp[i(kx - \omega t)])$$

$$= -c_s^2 \nabla \rho_a \exp[i(kx - \omega t)] - \rho_0 \nabla \phi_a \exp[i(kx - \omega t)]$$

$$-i\omega \rho_0 \vec{v}_a \exp[i(kx - \omega t)]$$

$$= ik c_s^2 \rho_a \vec{x} \exp[i(kx - \omega t)] - ik \rho_0 \phi_a \exp[i(kx - \omega t)] \vec{x}$$

$$\omega \rho_0 v_{a,x} = k(c_s^2 \rho_a + \rho_0 \phi_a)$$

$$\omega \rho_0 \left( \frac{\omega \rho_a}{k \rho_0} \right) = k c_s^2 \rho_a - k \rho_0 \left( \frac{4\pi G \rho_a}{k^2} \right)$$

$$\boxed{\omega^2 = c_s^2 k^2 - 4\pi G \rho_0}$$

Dispersion relation, describing the dispersion of the plane wave solution (relates spatial frequency  $k$  to temporal frequency  $\omega$ ).

## Implications:

Assume perturbation with short wavelength (large  $k$ )

$$k \gg 1$$

$$\text{and } c_s^2 k^2 - 4\pi G \rho_0 > 0$$



therefore  $\omega$  is a real number (pos. or neg.)

density:  $\rho = \rho_0 + \rho_a \exp[i(kx - \omega t)]$

(uniform background density with small oscillation in space and time on top of it)

since  $|\exp[i(kx - \omega t)]| < 1$  everywhere, the oscillation does not grow

Assume perturbation with long wavelength

$$k \ll 1$$

$$c_s^2 k^2 - 4\pi G \rho_0 < 0$$

therefore  $\omega$  is an imaginary number (pos. or neg.)

$\boxed{\exp[-i\omega t]}$  decays to zero (pos. root of  $\omega^2$ ) or grows to infinity (neg. root of  $\omega^2$ )

At least one solution of the perturbation will not remain small, it will grow: this is an instability.

Arbitrary small perturbations will grow to be large!

Critical size scale beyond which perturbations (only stabilized by pressure) must grow to non-linear amplitude (determined by sign flip of  $\omega$ ):

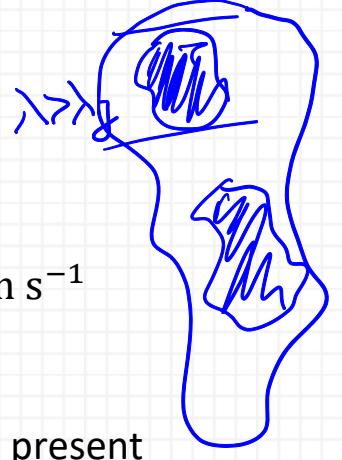
$$\omega = 0, \Rightarrow \boxed{k_J = \sqrt{\frac{4\pi G \rho_0}{c_s^2}}}$$

The corresponding wavelength is:

$$\boxed{\lambda_J = \frac{2\pi}{k_J} = \sqrt{\frac{\pi c_s^2}{G \rho_0}}} \quad \leftarrow$$

This is known as the Jeans length.

Associated mass scale: Jeans mass  $M_J = \rho \lambda_J^3$



Typical example: GMC  $\rho_0 = 100 m_p, c_s = 0.2 \text{ km s}^{-1}$

$$\lambda_J = 3.4 \text{ pc}$$

- ⇒ every GMC is larger, and perturbations will always be present
- ⇒ molecular clouds cannot be stabilized by gas pressure against collapse

How fast does the perturbation grow?

GMC example (size 50 pc):  $k = \frac{2\pi}{50 \text{ pc}} = \underline{0.12 \text{ pc}^{-1}}$

$$\frac{c_s^2 k^2}{4\pi G \rho_0} = 0.005, \text{ and } \omega \approx \pm i \sqrt{4\pi G \rho_0}$$

Taking the neg.  $i$  root (growing mode)

$$\rho_1 \propto \exp\left(\left[4\pi G \rho_0\right]^{\frac{1}{2}} t\right) \quad |$$

⇒ e-folding time for the disturbance to grow is  $\sim 1/\sqrt{G\rho_0}$

Definition: free-fall time

$$t_{ff} = \sqrt{\frac{3\pi}{32 G \rho_0}}$$

$$\sim \frac{1}{\sqrt{G\rho}}$$

characteristic time-scale for a medium with negligible pressure-support to collapse.

## 4.2.2 Magnetic Support and Magnetic Critical Mass

Magnetic terms also opposes collapse.

Consider a uniform spherical cloud of radius  $R$  threaded by a magnetic field  $\vec{B}$  (uniform inside of the cloud, outside it quickly drops down to the uniform, but much smaller background field  $\vec{B}_0$ )

Virial theorem:

$$\mathcal{B} = \frac{1}{8\pi} \int_V B^2 dV + \int_S \vec{r} \cdot \mathbf{T}_M \cdot d\mathbf{S}$$

with

$$\mathbf{T}_M \equiv \frac{1}{4\pi} \left( \vec{B} \vec{B} - \frac{B^2}{2} \mathbf{I} \right)$$

By assumption, the magnetic pressure inside is dominated by the magn. field inside the cloud:

$$\frac{1}{8\pi} \int_V B^2 dV \approx \frac{B^2 R^3}{6}$$

The surface magn. pressure term:

$$\int_S \vec{r} \cdot \mathbf{T}_M \cdot d\mathbf{S} = \int_S \frac{B_0^2}{8\pi} \vec{r} \cdot d\mathbf{S} \approx \frac{B_0^2 R_0^3}{6}$$

The magnetic flux passing through the cloud is  $\Phi_B = \underline{\underline{\pi B R^2}}$

The same field lines need also to pass through the virial surface (enclosing the cloud at all times)  $\Phi_B = \pi B R_0^2$

$$\mathcal{B} \approx \frac{B^2 R^3}{6} - \frac{B_0^2 R_0^3}{6} = \frac{1}{6\pi^2} \left( \frac{\Phi_B^2}{R} - \frac{\Phi_B^2}{R_0} \right) \approx \frac{\Phi_B^2}{6\pi^2 R} \quad | \quad R \ll R_0$$

Compare with gravitational term for a uniform cloud of mass  $M$ :

$$\mathcal{W} = -\frac{3}{5} \frac{GM^2}{R}$$

$$\underline{\underline{\mathcal{B} + \mathcal{W}}} = \frac{\Phi_B^2}{6\pi^2 R} + \underline{-\frac{3}{5} \frac{GM^2}{R}} \equiv \underline{\underline{\frac{3G}{5R} (M_\Phi^2 - M^2)}}$$

where

$$M_\Phi^2 \equiv \sqrt{\frac{5}{2}} \left( \frac{\Phi_B}{3\pi G^{1/2}} \right)$$

$M_\Phi$ : magnetic critical mass (const. since  $\Phi_B = \text{const}$ , because of flux freezing)

$$M > M_\Phi: \Rightarrow \mathcal{B} + \mathcal{W} < 0$$

magnetic force is unable to stop collapse

cloud is called magnetically supercritical

$$M < M_\Phi: \Rightarrow \mathcal{B} + \mathcal{W} > 0$$

gravity is weaker than magnetism

cloud is called magnetically subcritical

since  $\mathcal{B} + \mathcal{W} \propto 1/R$  the resistance grows if the cloud shrinks

A magnetically subcritical cloud will never collapse because magnetism will always stabilize it at a finite radius.

The cloud needs to reduce  $\Phi_B$  (only possible via e.g. ambipolar diffusion)

For real clouds Tomisaka (1998) gives:  $M_\Phi = 0.12 \frac{\Phi_B}{G^{1/2}}$

ideal cloud 0.17

Observation of  $B$  is difficult, possible for large sample (assuming random orientation)

⇒ observations indicate that magnetic fields in molecular clouds are not strong enough (by themselves) to prevent gravitational collapse)

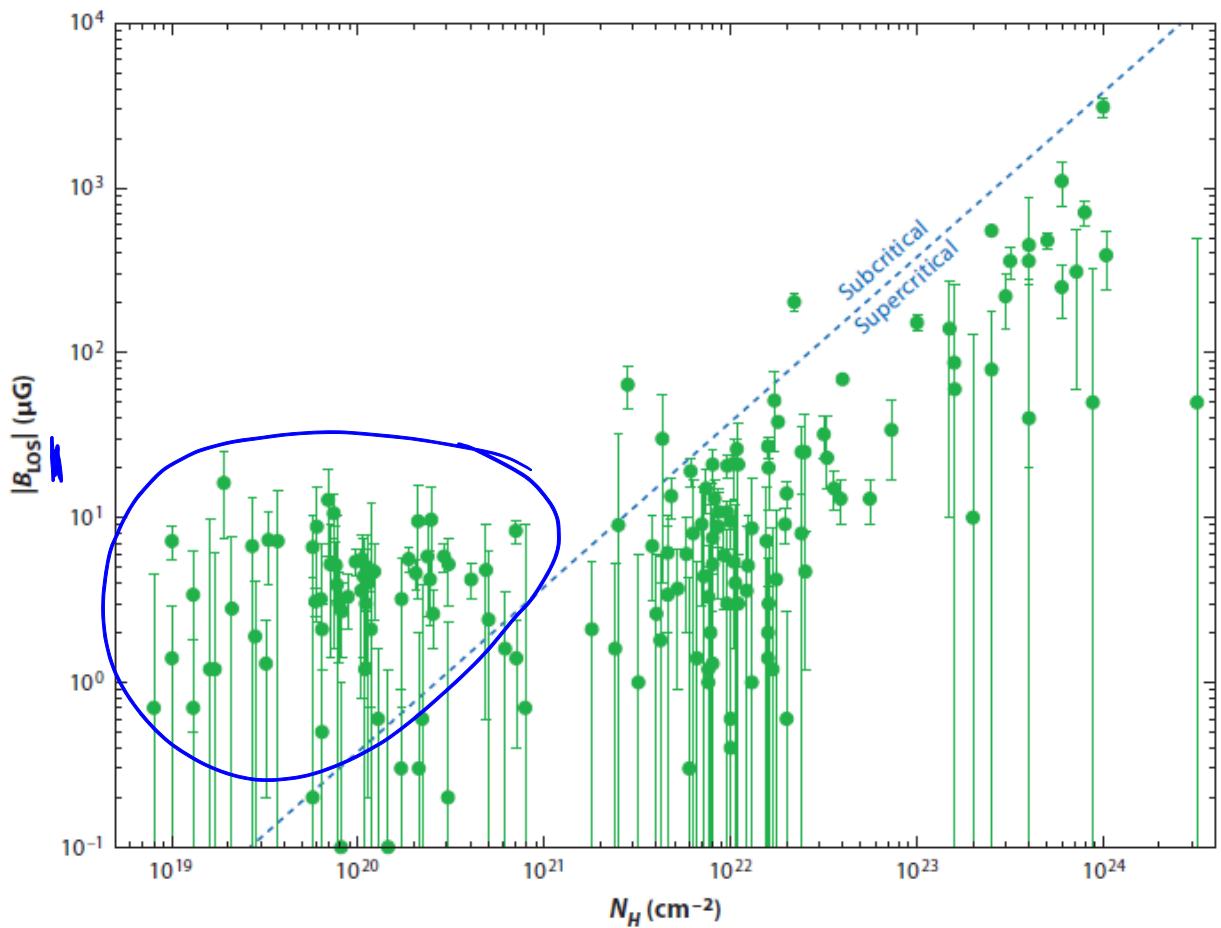


Abbildung 1 Measurements of the line of sight magnetic field strength versus total gas column density (Crutcher 2012)

### 4.3 PRESSURELESS COLLAPSE

Simplest case of initially-spherically cloud with initial density  $\rho(r)$ .

Enclosed mass:

$$M_r = \int_0^r 4\pi r'^2 \rho(r') dr'$$

or equivalently:

$$\frac{\partial M_r}{\partial r} = 4\pi r^2 \rho$$

In spherical coordinates:

$$\frac{\partial}{\partial t} \rho + \nabla \cdot (\rho \vec{v}) = 0$$

$$\frac{\partial}{\partial t} \rho + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \rho v) = 0$$

v: radial gas velocity

rewrite in terms of mass:

$$\begin{aligned}\frac{\partial}{\partial t} M_r &= 4\pi \int_0^r r'^2 \frac{\partial}{\partial t} \rho(r') dr' & \frac{\partial}{\partial t} \rho &= -\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \rho v) \\ &= -4\pi \int_0^r \frac{\partial}{\partial r'} (r'^2 \rho v) dr' \\ &= -4\pi r^2 \rho v = -v \frac{\partial}{\partial r} M_r\end{aligned}$$

Motion of gas: Lagrangian version of momentum equation

$$\rho \frac{D\mathbf{v}}{Dt} = -\frac{\partial}{\partial r} P - \vec{f}_g$$

isothermal  $P = \rho c_s^2$   
 $\vec{f}_g = -GM_r/r^2$

$$\boxed{\frac{D\mathbf{v}}{Dt} = \frac{\partial}{\partial t} \mathbf{v} + \mathbf{v} \frac{\partial}{\partial r} \mathbf{v} = -\frac{c_s^2}{\rho} \frac{\partial}{\partial r} \rho - \frac{GM_r}{r^2}}$$

total time derivative of  $f(r, t)$   
 $\frac{D}{Dt} f(r, t) = \frac{\partial f}{\partial t} + \frac{\partial f}{\partial r}$

Assumption:  $c_s = 0$  (pressure proportional to mass and  $c_s \sim const.$ )

gravity grows with  $1/R$ , soon after collapse starts  
 pressure will become unimportant

⇒ pressureless collapse

$$\boxed{\frac{D\mathbf{v}}{Dt} = -\frac{GM_r}{r^2}}$$

grav. acceleration of a shell is just proportional to all the enclosed mass,  
 which is constant.

$$\mathbf{v} = \dot{\mathbf{r}} = -\sqrt{2GM_r} \left( \frac{1}{r_0} - \frac{1}{r} \right)^{1/2}$$

$$r(t=0) = r_0$$

$$r = r_0 \cos^2 \xi$$

$$-2r_0(\cos \xi \sin \xi) \dot{\xi} = -\sqrt{\frac{2GM_r}{r_0}} \left( \frac{1}{\cos^2 \xi} - 1 \right)^{\frac{1}{2}}$$

$$2(\cos \xi \sin \xi) \dot{\xi} = \sqrt{\frac{2GM_r}{r_0^3}} \tan \xi$$

$$2 \cos^2 \xi d\xi = \sqrt{\frac{2GM_r}{r_0^3}} dt$$

$$\xi + \frac{1}{2} \sin 2\xi = t \sqrt{\frac{2GM_r}{r_0^3}}$$

Collapse complete when  $r = 0$ , i.e.  $\xi = \pi/2$

$$t = \frac{\pi}{2} \sqrt{\frac{r_0^3}{2GM_r}}$$

If the gas started with uniform density  $\rho$  then  $M_r = \left(\frac{4}{3}\right) \pi r_0^3 \rho$ . Then we have:

$$t = t_{ff} = \sqrt{\frac{3\pi}{32G\rho}}$$

This is the free-fall time, required for a uniform sphere of pressureless gas to collapse to infinite density.

Compare with growth time for Jeans instability:  $\sim 1/\sqrt{G\rho}$

For a uniform fluid  $\Rightarrow$  synchronized collapse (all gas reaches center simultaneously)

Assume  $\rho = \rho_c \left(\frac{r}{r_c}\right)^{-\alpha}$  where ( $\alpha > 0$ )

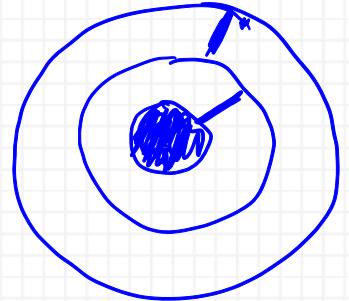
$$M_r = \frac{4}{3-\alpha} \pi \rho_c r_c^3 \left(\frac{r}{r_c}\right)^{3-\alpha}$$

then the collapse time is:

$$t = \sqrt{\frac{(3-\alpha)\pi}{32G\rho_c}} \left(\frac{r_0}{r_c}\right)^{\alpha/2}$$

$t \propto r_0^{\alpha/2}$ , and  $> 0$ , so the collapse time increases with initial radius  $r_0$

Inside-out Collapse: in centrally concentrated objects inner parts collapse before the outer parts

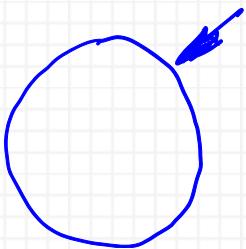


What is the density profile near the center?

For  $r \ll r_0$   $v \approx v_{ff} = -\sqrt{\frac{2GM_r}{r}}$

free-fall velocity  $v_{ff}$ : characteristic speed of an object collapsing freely onto a mass  $M$ .

$$\frac{\partial}{\partial t} M_r = -v \frac{\partial}{\partial r} M_r = -4\pi r^2 v \rho$$



near the star ( $v \approx v_{ff}$ ), then

$$\rho = \frac{\left(\frac{\partial M_r}{\partial t}\right) r^{-\frac{3}{2}}}{4\pi \sqrt{2GM_r}}$$

For a short time interval  $\frac{\partial M_r}{\partial t} \approx \text{const}$ , then  $\rho \propto r^{-3/2}$

We can also estimate the accretion time this implies:

Consider a core of mass  $M_c = \left[\frac{4}{3-\alpha}\right] \pi \rho_c r_c^3$ . Its last mass element arrives at the center at:

$$t_c = \sqrt{\frac{(3-\alpha)\pi}{32G\rho_c}} = \underbrace{\sqrt{\frac{3-\alpha}{3}}}_{\text{blue bracket}} t_{ff}(\rho_c)$$

so the time-averaged accretion rate is

$$\langle \dot{M} \rangle = \sqrt{\frac{3}{(3-\alpha)}} \frac{M_c}{t_{ff}(\rho_c)}$$

Assume the core is a Bonnor-Ebert sphere. Its maximum mass is

$$M_{BE} = 1.18 \frac{c_s^4}{\sqrt{G^3 P_s}}$$

$P_s$ : pressure at the surface of the sphere

Assume, that the surface of the core is in thermal pressure balance with its surroundings:  $P_s = \rho_c c_s^2$

$$M_{BE} = 1.18 \frac{c_s^3}{\sqrt{G^3 \rho_c}}$$

substitute into accretion rate, assume  $\sqrt{\frac{3}{(3-\alpha)}} \approx 1$

$$\langle \dot{M} \rangle \approx \frac{\frac{c_s^3}{\sqrt{G^3 \rho_c}}}{\frac{1}{\sqrt{G \rho_c}}} = \frac{c_s^3}{G}$$

If we know  $c_s$  we can calculate the accretion rate of any object that is marginally stable based on thermal pressure support.

$$c_s = 0.19 \text{ km s}^{-1} \Rightarrow \dot{M} \approx 2 \times 10^{-6} M_\odot \text{ yr}^{-1}$$

For a typical stellar mass of few  $0.1 M_\odot$  we find a **characteristic star formation time** of order  $10^5$ - $10^6$  yr.